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# Shapes of Trees within a Controlled Sphere of Light

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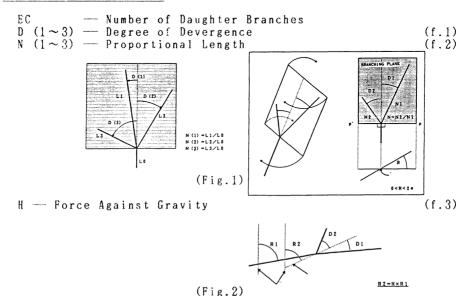
#### Keywords: Tree Shapes, Environment, Light, Computer Simulation

All plants have common chalacteristics of growth and reaction to the environment. The affect of the environmental conditions on the different types of plants determines their shapes.

Most of the major growth and reaction characteristics of trees have been selected through observation and analysis. A system to control and measure the light conditions for an actual tree has been set up.

Computer simulation has been employed in order to show the variations of shapes produced by different types of trees under pre-determined light conditions.

#### 1. BRANCHING SYSTEM



U — Tendencies in Frequency of Branching Planes (f.4)

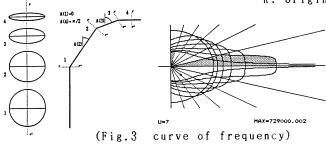
With exeptions, the more horizontal the mother branches, the more frequent the horizontal branching plane is.

U'=1- | 
$$(\pi \div 2-A)$$
 |  $\div (\pi \div 2)$   
A: angle of the mother branch to the vertical

$$(-\pi \div 2 < R < \pi \div 2)$$

$$r = R \div (\pi \div 2)$$

$$R' = (U' \times r^{u} + (1 - U') \times r) \times (\pi \div 2)$$
(2a)



#### (f.5)2. THREE FACTORS IN TRUNK CHARACTERISTICS (V)

- I. High Growth Rate
- $F = F \times V$
- II. High Branch Frequency
- VC = VIII. Strong Force Against Gravity
- $A = A \div V$

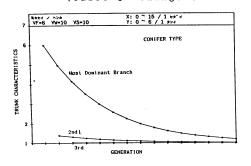
F: Growth Rate

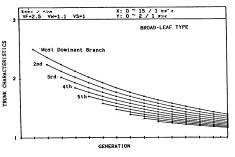
VC: Branch Frequency

A: Angle of Trunk to the Vertical

# OTHER TRUNK CHARACTERISTICS

(Table 1 change in trunk characteristics with age)





# 3. CURVE OF BRANCHES

D — Tendency of Branches to Curve Downward with Age (f.6)

AA<sub>P</sub> = AA<sub>P-1</sub> + SIN A<sub>P</sub> × D ÷ ((N-N<sub>P</sub>)<sup>1·2</sup> × F<sub>P</sub>)

P: Number of Brunch Points

A: Angle of Branch to the Vertical

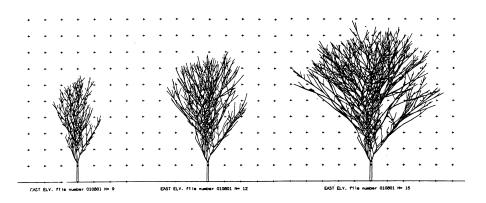
AA: Degree of Curving

N: Generation (discrete time in computer simulation)

F: Rate of Growth

H= 0 D= .1 S= .95 SH= 0 (vo= 1.1)

(Fig. 4 in branches which tend to curve downward the force against gravity tends to strong, and vice versa.)



(Fig. 5 the downward growth curve provides the necessary outside surface area of the crown to permit further branching)

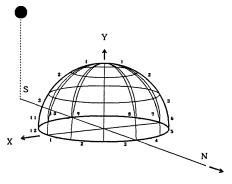
# 4. TWINING CHARACTERISTICS (Ability to Sense and React to the Environment) RD — Maximum Angle of Rotation (f.7)SUBSTITUTED SPHERE FOR SPHERES OF LEAVES WITHIN CUBES (Fig. 6) INCLUDED EAST ELV. file number 01FAST ELV. file number 011002 N= 12 FAST ELV. file number 011002 N= 18 EXCLUDED

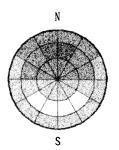
(Fig.7 when the twining character is included in the program, it produces a more typical tree shape)

EAST ELV. file number 011001 N= 18

FAST ELV. file number 01EAST ELV. file number 011001 N= 12

# 5. SPHERE OF INCOMING LIGHT



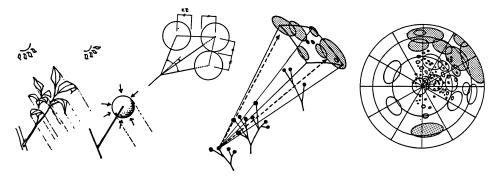


(Fig. 8 possible to control variations in areas of intencity)

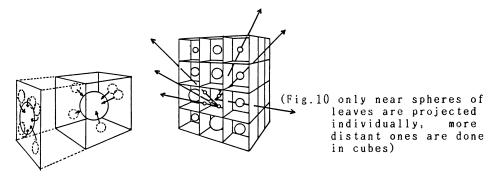
# 6. SPHERE TO SCREEN OUT LIGHT

KK - Radius of Sphere

(f.8)



(Fig.9 the assumed spheres of leaves are projected onto a spherical screen)



The Minimum Amount of Light Necessary to Prevent Stems from Dying.

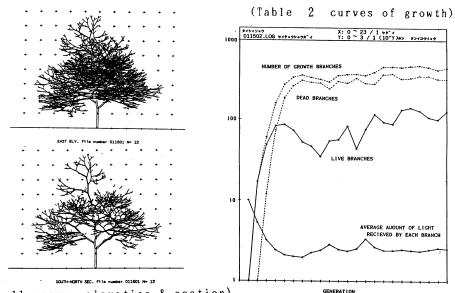
FW — Ratio of Amount of Light Recieved by the Sphere of Leaves to Entire Incoming Light (f.9)

#### SHAPES OF TREES WITHIN A SPHERE OF LIGHT

The computer simulation turned out to be very similer to actual growth patterns.

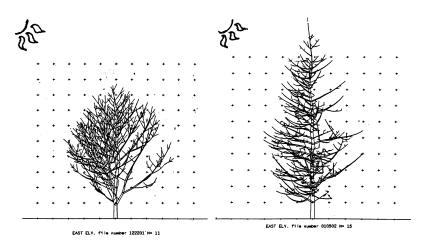
Live branches have a very rapid growth rate in early generations after the tree has produce a crown the growth rate declines dramatically.

Even in a constant environment without natural variations, the zig-zag growth rate curve of the natural environment remaind valid.



(Fig. 11 crown; elevation & section)

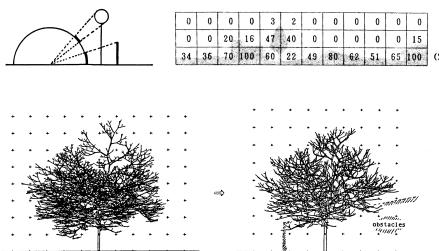
Irregular light intensity over the light sphere causes irregular growth of the crown, with the light intense area having the more dense growth.



(FIG. 12 east elevation)

Two Types of Obstacles, Stationary and Live, can be Painted on the Spherical Screen.

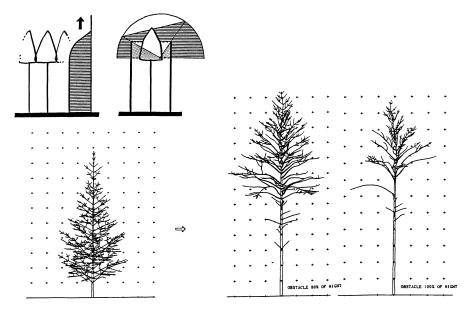
# I. Stationary Obstacles



(Fig. 13 stationary obstacles have a constant effect on the resultant tree shape)

#### II. Live Obstacles

SOUTH ELV. file number 011601 N= 12



(Fig.14 the resultant shape of tree with a live obstacle 80% or 100% of its hight in a planted forest can be simulated)

# 7. PROGRAM FLOWCHART & VARIATIONS OF SHAPES

